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# FORECASTING STOCK MARKET INDEX BASED ON PATTERN-DRIVEN LONG SHORT-TERM MEMORY

Abstract. Stock trend prediction is an important area of study for researchers and practitioners. In recent years, along with traditional statistical prediction models, machine learning and deep learning techniques have been increasingly adopted in various financial studies. Long Short-Term Memory (LSTM) is one of the deep learning models for predicting time-series data. In the case of vanilla LSTM, shared weights are learned based on all available data; hence, it is difficult to accurately learn patterns and predict the future value from a subset of data. In this paper, a pattern-driven hybrid model that combines an LSTM with an unsupervised learning algorithm is proposed for precise prediction of stock prices. The performance of the hybrid model is evaluated using Korea stock index data. The results demonstrate that the proposed model outperforms traditional recurrent neural network (RNN) and LSTM models.

*Keywords:* Long Short-Term Memory, Forecasting, Pattern Clustering, Stock Index, Time-series Analysis.

# JEL Classification:C45, E37

# 1. Introduction

Forecasting has been a subject of interest for a long time, and this interest has led to a great number of studies in diverse fields, especially finance. However, financial time-series forecasting, particularly stock price forecasting, has been a

challenging problem for researchers and investors due to financial sectors having high volatility and time-varying environments. Thus, various stock market prediction approaches have been proposed. These methods include simple statistical linear regression models to state-of-the-art deep learning-based models.

For decades, traditional statistical models, such as the autoregressive moving average and autoregressive integrated moving average models, have been widely used in economics for time-series prediction, primarily due to their ability to model linear relationships between the input and output (Box et al., 2015; Cheong, 2013; Idrees et al., 2019). However, linear assumptions often lack sufficient evidence (Enkeand Thawornwong, 2005); thus, adopting artificial neural network algorithms in the prediction of financial data has attracted increasing attention in industry and academia. Neural networks have rapidly gained preference because they demonstrate great suitability in handling incomplete, missing, or noisy data without requiring assumptions about the data distribution (Vellido et al., 1999).

Numerous applications of ANNs have been studied, some of which have successfully predicted a wide range of financial data indicators (Refenes et al., 1997; Vanstone & Finnie, 2009; Zhang et al., 1998). Enhanced neural networks have also been introduced as forecasting methods. For example, Maknickiene et al. (2011)applied a recurrent neural network (RNN) to investigate financial market predictions. Besides, a long short-term memory (LSTM) network, which is a variation of an RNN to solve vanishing gradient problems, has been implemented extensively in recent studies (Moon and Kim, 2019; Nelson et al., 2017). The remarkable performance of such methods demonstrates the superiority of LSTM on time-series data. However, a limitation exists, e.g., LSTMs tend to prefer recent data, which affect shared parameters significantly (Fu et al., 2018). As financial time-series data involve time-dependent relationships, LSTM often fails to capture such dynamics (Oh et al., 2019).

Despite the high performance of LSTM, even the slightest improvement is desirable because this has a positive influence on financial investments. Therefore, improving the efficiency of forecast models remains a primary concern. Accordingly, hybrid models have been proposed. For example, Bildirici and Ersin (2009), Kristjanpoller et al. (2014), Wang and Que (2018), and Yang and Lin (2015) demonstrated hybrid models that combine different artificial intelligence techniques with traditional forecasting approaches. In addition, Pulido et al. (2014) suggested a combination of neural network and fuzzy aggregation based on particle swarm optimization to predict the Mexican stock exchange. Baek and Kim (2018) developed a modular architecture comprising two LSTM networks to refine the resulting deterioration in prediction accuracy. Ramos-Pérezet al. (2019) proposed a financial forecasting system using machine learning techniques with neural

networks. Overall, hybridized models outperform conventional single models by yielding lower test errors.

This paper presents a hybrid pattern-driven LSTM (P-LSTM) model, which combines unsupervised and supervised learning algorithms, to solve the limitation of LSTM in which patterns in data are not learned precisely due to weights being shared between cells. The proposed P-LSTM model clusters financial time-series data based on subsequences of the same pattern and trains them separately for stable learning of weights.

The remainder of this paper is organized as follows. Section 2 summarizes the two methodologies adopted to develop the proposed hybrid model. Section 3 discusses the framework of the proposed P- LSTM model. Section 4 provides an in-depth discussion of experimental setups and processes, and, in Section 5, the experimental results are provided with detailed analysis. Finally, conclusions are given in Section 6.

#### 2. Background

This section describes the architectures of the two key models that adopt the pattern-driven hybrid model, i.e., the balanced iterative reducing and clustering using hierarchies (BIRCH) clustering and LSTM algorithms.

### 2.1 BIRCH clustering algorithm

BIRCH, developed by Zhang et al. (1996), is a typical integrated hierarchical clustering algorithm applicable to very large datasets and is known to achieve high-quality clustering with only one traversal. Its high efficiency is a result of the clever use of available memory to derive the best quality sub-clusters while reducing processing costs. In BIRCH, not every data point is equally crucial for clustering purposes. Consequently, the BIRCH clustering method provides a robust solution for managing noise (Thilagavathi et al. 2013). Moreover, when a Euclidean or Manhattan distance measure is used, BIRCH is preferred because the data attributes are continuous (Chiu et al. 2001).Such aspects make BIRCH algorithm a primary candidate for clustering.

BIRCH is mainly composed of two phases. It first performs pre-clustering in which dense regions of data points are represented in summary statistics called clustering feature (CF). Then, hierarchical clustering is conducted to cluster the set of summaries. The CF represents the characteristics of a cluster and is denoted (n, LS, SS), where n is the number of data in a sub-cluster, LS is the linear sum of the points, and SS is the sum of the squared of the points. New CF can be obtained by adding the CFs of two disjoint clusters as follows.

 $CF_1 + CF_2 = (n_1 + n_2, LS_1 + LS_2, SS_1 + SS_2)$ 

The information in the CF is adequate to achieve high-quality clustering. Thus, the BIRCH algorithm is memory-efficient because it does not require the whole dataset.

The CF comprises the nodes in a CF tree that is an in-memory data structure acting as the core of the BIRCH clustering algorithm. In a CF tree, leaf nodes form the non-leaf node, and non-leaf nodes form the root. The parameters of the CF tree are branching factor B, threshold T, and the number of entries in a leaf node L. Branching factor B establishes the limiting number of sub-clusters for each non-leaf node, and threshold T is the maximum radius of a cluster in a leaf node. If threshold T is too small, significant space could be taken; thus, it is recommended to begin from 0 and increment the threshold slowly (Bing et al. 2004).

The steps of the BIRCH clustering algorithm are summarized as follows.

- 1. Build a CF tree to load data to the memory. Reconstruct the tree if memor y is exhausted.
- 2. Resize the dataset by removing outliers to adjust the size of the CF tree.
- 3. Use the existing clustering algorithm on CF entries.
- 4. (Optional) Refine the cluster by fixing incorrectly assigned data points.

#### 2.2 Long Short-term Memory

Recurrent neural networks (RNN) are remarkably powerful models that process sequential patterns through internal loops; however, it is frequently difficult to train RNNs when handling long time lags due to back propagated error blowing up or decaying exponentially, also known as exploding and vanishing gradients, respectively. To address the vanishing gradients problem, the LSTM architecture was developed by Hochreiter and Schmidhuber (1997). LSTM introduces an innovative concept called a memory block, which is essentially an accumulator of state information.

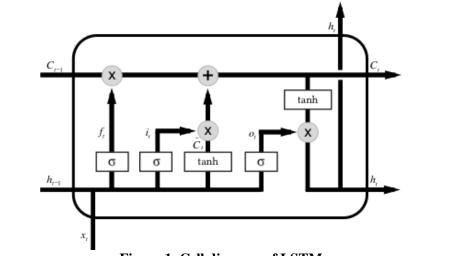


Figure 1. Cell diagram of LSTM

As shown in Fig. 1, the memory block comprises a memory cell and three main gates. The memory cell  $c^t$  has a recurrently self-connected linear unit, an input gate  $i^t$  that allows an incoming signal to alter (or block) the state of the memory cell, a forget gate  $f^t$  that modulates the memory cell's connection to keep only the relevant information from its previous state, and an output gate  $o^t$  allowing (or preventing) the state of the memory cell to influence other neurons. These components control the information flow and allow a gradient to be trapped in the cell, which prevents the gradient from becoming increasingly unstable.

Mathematical expressions for the most common LSTM architecture, i.e., with forget gates, are given as follows.

Input gate: $i^t = \sigma(W_i x^t + U_i h^{t-1} + b_i)$	(1)
Forget gate: $f^t = \sigma(W_f x^t + U_f h^{t-1} + b_f)$	(2)
Memory cell: $c^t = i_t \odot \tilde{c}_t + f_t \odot c_{t-1}$	(3)
Input modulate gate: $\tilde{c}^t = \tanh(W_c x^t + U_c h^{t-1} + b_c)$	(4)
Output gate: $o^t = \sigma(W_o x^t + U_o h^{t-1} + b_o)$	(5)
Block output: $h^t = o^t \odot tanh(c^t)$	(6)

Here,  $\tilde{c}^t$  determines the amount of new information received in the cell state,  $x^t$  is the input vector at time t,  $h^t$  is the hidden layer vector, W denotes input weighted matrices, U denotes recurrent weight matrices, and b denotes the bias vectors of LSTM.  $\sigma(\cdot)$  is a pointwise nonlinear activation function, i.e., logistic sigmoid  $\left(\frac{1}{1+e^{-x}}\right)$  in this case. Note that elementwise multiplication is denoted  $\Theta$ .

### 3. Proposed Pattern-driven LSTM

The proposed P-LSTM framework has three primary stages, as shown in Fig. 2. The first stage involves pre-processing the input time-series data. The time-series data are partitioned to be the same size as the timestep in the LSTM network. Then, each vector set is paired with a Y value, i.e., the closing price of the following day. These paired sets are divided into training and testing data. Each X value is min/max scaled from 0 to 1 based on their X vector set for the clustering process and Y values are also scale during the min and max of the corresponding X vector set.

Patterns are defined in the second stage. Here, M clusters are classified by applying the BIRCH clustering algorithm to data with essentialinput features. These clusters depict all possible patterns in the provided data. Subsequently, all the batches in the training data are then distributed appropriately to the clusters, thereby generating a new form of training data. Additionally, batches of testing data are fed into the trained BIRCH model for assignment to a proper cluster.

In the last stage, a LSTM network is built for each cluster. Here, the LSTM network is trained using the training data collected in the corresponding cluster. Finally, the testing data from the same cluster is fed into the trained LSTM neural network to perform the prediction.

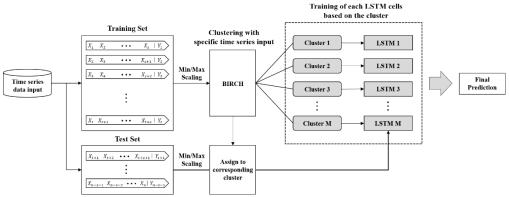


Figure 2. Architecture of proposed P-LSTM hybrid model

# 4. Experimental Setup

### 4.1 Data and pre-processing

Daily data from the Korean stock market indexes, i.e., Korea Composite Stock Price Index (KOSPI) and Korea Securities Dealers Automated Quotation (KOSDAQ) were used to evaluate the performance of the prediction models. As seen in Table 1 and Figure 3, the data comprise 4593 daily records from January 2, 2001 to July 31, 2019. The data were split into training data (80%) and testing data

(20%) after batch pre-processing. Here, the training data were used to train the LSTM models, and the testing data were used to validate the proposed model.

Each data point is defined as  $X_t$ , and comprises five indicators: open price (stock price at the start of each trading day), high price (highest price of each trading day), low price (lowest price of each trading day), close price (stock price at the end of each trading day), and volume (number of shares traded in a security during each trading day).

Note that the input variables were pre-processed to maximize the performance of the proposed P-LSTM model. First, the indicators of each day were bundled into a vector  $X_t$ . Then, several of these vectors were put together to form the batch  $\tilde{X}$  by considering the size of the timestep (n) of the corresponding LSTM cell. As the magnitude of data varies, which prevents accurate clustering, each time-series vector set comprising consecutive days was min/max scaled as follows.

$$x' = \frac{x - x_{min}}{x_{max} - x_{min}} \tag{7}$$

Here, x is the original value, x' is the scaled value, and  $x_{max}$  and  $x_{min}$  are the maximum and minimum values in each batch  $\tilde{X} = \{X_1, X_2, \dots, X_n\}$ , respectively.

The Y value in each batch are also min/max scaled based on the minimum and maximum values of the corresponding  $\tilde{x}$  vector set. In this study, the data dimension was set 20 days because, in this given period, the features are most effective as a moving average in the stock market.

Table 1. Summary of training data and test dataset after batch preprocessing

Dataset	Train period (sample)	Test period (sample)
KOSPI	2001/01/02 ~ 2015/11/05 (3658)	2015/11/06 ~ 2019/07/31 (915)
KOSDAQ	2001/01/02 ~ 2015/11/05 (3658)	2015/11/06 ~ 2019/07/31 (915)

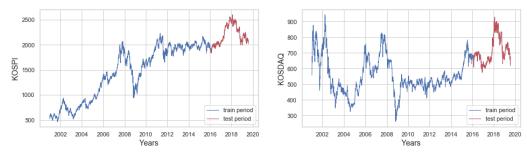


Figure 3. KOSPI (left) and KOSDAQ (right) index

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### **4.2 Pattern Clustering**

Pattern clusters were classified with the 3658 pre-processed training data from the previous step based on the BIRCH clustering algorithm. For clustering, min/max scaled values between 0 and 1 were used. Then, the 915 pre-processed test data were assigned to the corresponding clusters based on the trained model.

Here, the BIRCH hyperparameters were set to appropriate values through preliminary experiments based. First, the number of clusters was set to 8to prevent the number of data in each cluster from becoming too small relative to the limited number of data, although better patterns can be classified using a greater number of clusters. Second, the threshold and branching factor were set to 0.2 and 20, respectively, to distribute data evenly among clusters without destroying the pattern. As a result, eight clusters were obtained. Figures 4 and 5 show the number of allocated training and testing samples from KOSPI and KOSDAQ in each cluster.

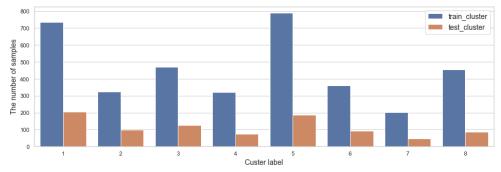


Figure4. Number of training and test samples in each cluster for KOSPI

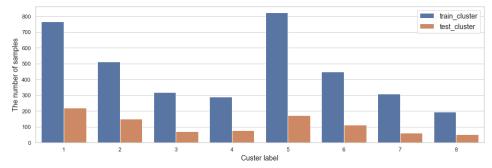


Figure 5. Number of training and test samples in each cluster for KOSDAQ

# **4.3 Model Hyperparameter**

An LSTM neural network was applied to each cluster. Thus, the number of networks was equal to the number of clusters. For the LSTM hyperparameters, optimum values were found by conducting inductive experiments. To prevent the model from overfitting, early-stopping was employed to stop training as required. Except for the epochs, the other hyperparameters were kept constant to maintain the universality of the experiment. The hyperparameters were set as follows: timestep = 20, learning rate = 0.001, input dimension = 5, hidden dimension = 1, and output dimension = 1 (the output dimension is the dimension of the closing price of the next day). Finally, the Adam optimizer and mean squared error were used as the optimization algorithm and loss function, respectively.

## **4.4 Evaluation Metrics**

The experimental results were analysed according to the mean absolute error (MAE), root mean square error (RMSE) and mean absolute percentage error (MAPE) metrics.

$$MAE = \frac{1}{n} \sum_{i=1}^{n} |y_i - f_i|$$
(8)

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (y_i - f_i)^2}$$
(9)

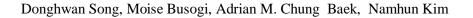
$$MAPE = \frac{1}{n} \sum_{i=1}^{n} \left| \frac{y_i - f_i}{y_i} \right|$$
(10)

Here,  $y_i$  and  $f_i$  are the actual and forecast values, respectively, and n is the number of forecasted values. The evaluation indexes of the M clusters were averaged using a simple arithmetic average method to facilitate the evaluation of the forecast results output by the proposed P-LSTM model.

## 5. Results

The KOSPI and KOSDAQ datasets were used to evaluate the effectiveness of the proposed P-LSTM model in forecasting actual financial time-series data. The prediction accuracy was compared to that of conventional RNN- and LSTM-based deep learning models.

Figures 6 and 8 show the patterns obtained when BIRCH clustering was applied to the KOSPI and KOSDAQ training data, and Figs. 7 and 9 show the clustered KOSPI and KOSDAQ testing data. The lines in the figures are the connections of  $X^4$  values, i.e., the closing price, from time (t-20) to time t. The x-axis represents the length of the time step (20 days), and the y-axis represents the min/max scaled closing price. These figures show that the line density depends on the number of samples, all eight clusters demonstrate different patterns, and the pattern of the testing clusters perfectly matches that of the trained cluster.



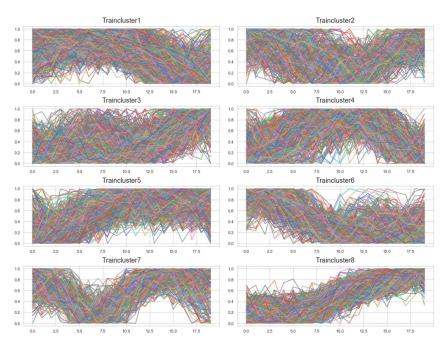


Figure 6. Visualization of KOSPI patterns for each training cluster classified using BIRCH algorithm

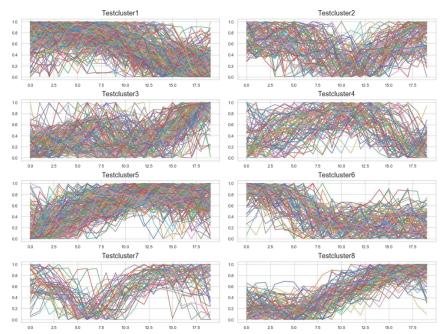


Figure 7. Visualization of KOSPI patterns for each testing cluster classified using BIRCH algorithm

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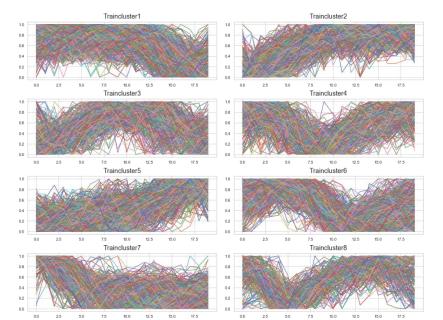


Figure 8. Visualization of KOSDAQ patterns for each training cluster classified using BIRCH algorithm

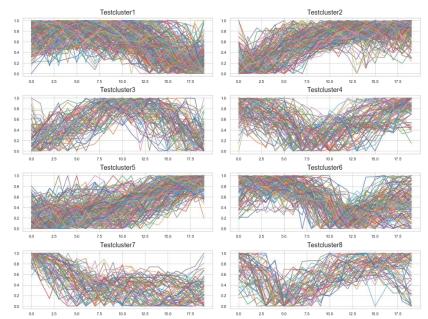


Figure 9. Visualization of KOSDAQ patterns for each testing cluster classified using BIRCH algorithm

			KOS	PI	KOSDAQ		
		Train	Test	Early Stopping epoch	Training	Test	Early Stopping epoch
Р-	Cluster 1	736	204	21	766	220	48
	Cluster 2	323	97	87	511	149	38
	Cluster 3	471	126	42	319	71	51
	Cluster 4	322	75	40	289	78	83
LSTM	Cluster 5	788	187	28	821	171	39
	Cluster 6	359	92	35	447	112	39
	Cluster 7	203	48	34	309	62	35
	Cluster 8	456	86	14	196	52	115
LSTM		3658	915	35	3658	915	49
RNN		3658	915	22	3658	915	34

Table 2.Number of Sample data and early-stopping epoch for each model

The number of sample data and epoch for each model are summarized in Table 2. For the proposed P-LSTM, the numbers of distributed samples according to the patterns are noted. The evaluation results of the testing data fed into the corresponding neural network are listed in Table 3. The average results obtained using the KOSPI data are 13.285 (MAE), 18.475 (RMSE), and 0.610 (MAPE), and the average results obtained using the KOSDAQ data are 6.887 (MAE), 9.413 (RMSE), and 0.948 (MAPE). The obtained results suggest that the values of cluster 7 for the KOSPI data and cluster 3 for the KOSDAQ data are optimum.

		KOSPI			KOSDAQ		
		MAE	RMSE	MAPE	MAE	RMSE	MAPE
P- LSTM	Cluster 1	15.110	19.517	0.704	8.184	10.969	1.169
	Cluster 2	13.530	17.650	0.635	6.505	9.156	0.878
	Cluster 3	9.754	13.722	0.437	8.798	11.537	1.188
	Cluster 4	12.697	19.384	0.587	5.368	7.851	0.740
	Cluster 5	11.783	15.392	0.534	5.329	7.246	0.718
	Cluster 6	15.213	20.513	0.692	6.391	8.366	0.884
	Cluster 7	14.151	20.632	0.674	7.930	10.241	1.124
	Cluster 8	14.042	20.987	0.616	6.592	9.940	0.886
	Mean	13.285	18.475	0.610	6.887	9.413	0.948
	Best	9.754	13.722	0.437	5.329	7.246	0.718

Table 3. Summary of P-LSTM forecasting evaluation results for each cluster

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Figures 10 and 11 compare the actual values of the KOSPI and KOSDAQ indexes to the min/max scaled values returned to the original exponential scale. Here, the x-axis represents the independent data samples within each cluster rather than continuous time-series data.

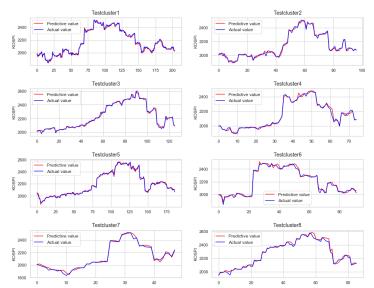


Fig. 10. Comparison of predicted data from P-LSTM and actual data for KOSPI in each cluster

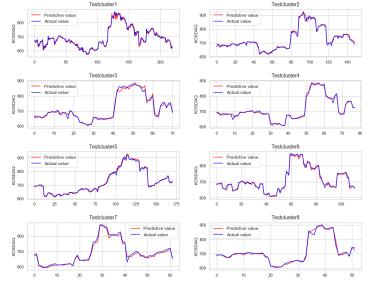


Fig. 11. Comparison of predicted data from P-LSTM and actual data for KOSDAQ in each cluster

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The testing data were also restored to the original index data to facilitate comparison with the actual indexes or the other models. The inverse scaled results compared to the results from the LSTM and RNN methods and the actual KOSPI and KOSDAQ values are shown in Fig. 12. As shown in Fig. 12 and Table 4, the pattern-based LSTM model captures the movement of the actual indexes as demonstrated by the lowest error compared to LSTM only or RNN.

Table 4 summarizes the test errors of the compared models. As can be seen, the proposed model demonstrates improvements over the RNN model of 49.07% (MAE), 45.80% (RMSE), and 46.51% (MAPE) for the KOSPI data, and 10.49% (MAE), 8.59% (RMSE), and 11.15% (MAPE) for the KOSDAQ data. Compared to the LSTM model, the proposed model demonstrated approximately 30.53% (MAE), 27.13% (RMSE), and 27.80% (MAPE) differences in performance for the KOSPI data, and 3.07% (MAE), 2.69% (RMSE), and 3.36% (MAPE) differences for the KOSDAQ data.

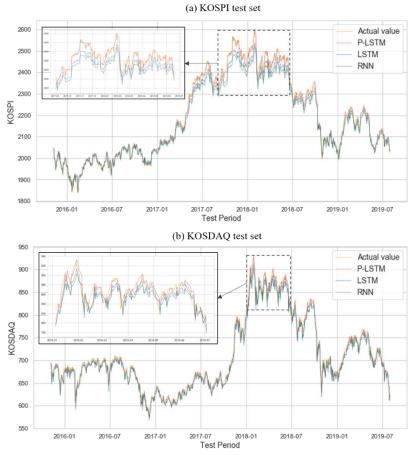


Fig. 12. Comparison of predicted and actual values for (a) KOSPI data and (b) KOSDAQ data

	KOSPI			KOSDAQ			
	MAE	RMSE	MAPE	MAE	RMSE	MAPE	
P-LSTM	13.187	18.142	0.605	6.857	9.448	0.948	
LSTM	18.983	24.898	0.838	7.074	9.709	0.981	
RNN	25.891	33.473	1.131	7.661	10.336	1.067	

#### Table 4. Comparison of test errors

#### 6. Conclusion

With technological advancements, academics have adopted deep learningbased methods to conduct meaningful studies into solving diverse time-series problems. In particular, RNN and LSTM models are commonly applied to such problems, and their architectures are frequently modified to improve predictive performance. However, due to their tendency to prefer recent inputs, they demonstrate limited efficacy when handling data over a period, e.g., financial timeseries data. Therefore, in this paper, we have proposed the P-LSTM model, which integrates LSTM into a classical unsupervised learning model, i.e., the BIRCH clustering algorithm, and works with an emphasis on a divide and conquer strategy. The proposed P-LSTM model (1) pre-processes time-series data by partitioning the data into a specific size and pairing to the closing price of the next day and then min/max scales in the range 0-1; (2) classifies patterns using the BIRCH clustering algorithm and assigns test data to proper clusters; and (3) builds individual LSTM neural networks for each cluster and feeds the test data for evaluation.

The predictive power of the proposed P-LSTM model was validated by applying it to the KOSPI and KOSDAQ indexes. According to the results, the MAE, RMSE, and MAPE values for the KOSPI data decreased to 30.53% (49.07%), 27.13% (45.80%), and 27.80% (46.51%), respectively, of the corresponding KOSPI forecasting errors of LSTM (RNN). Besides, the test MAE, RMSE, and MAPE values for the KOSDAQ data decreased to 3.07% (10.49%), 2.69% (8.59%), and 3.36% (11.15%), respectively, of the corresponding KOSDAQ forecasting errors of LSTM (RNN). These results demonstrate that the proposed P-LSTM model outperforms conventional RNN and LSTM models and is more suitable for financial time-series prediction problems than conventional networks because their unique structures make it possible to learn patterns contained in input sequences.

This study has significance because suggests a new approach to preprocessing and forecasting financial time-series data by combining learning techniques. Besides, the proposed P-LSTM model is not restricted to financial data, i.e., it can be applied to time-series data from other fields. Finally, the proposed network can extend research into hybrid frameworks.

Note that the effectiveness of the proposed P-LSTM model improves as the number of clusters increases, i.e., as more patterns are classified, more sophisticated predictions can be achieved. However, this increase of clusters undoubtedly leads to a reduced number of samples in each cluster, which results in the model prone to overfitting. Thus, in the future, solutions for insufficient data will be explored, such as data augmentation that reassembles time-series data with different properties based on patterns or using time-series data in minutes.

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